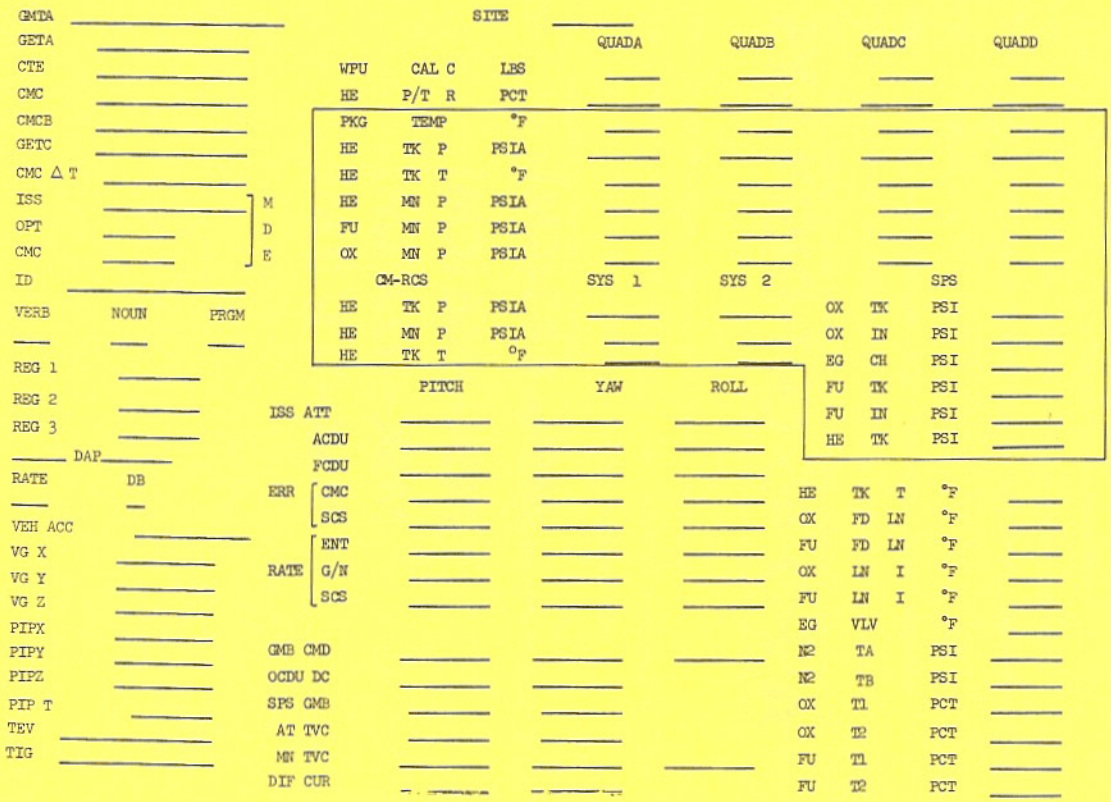
ASPO 45 CRT DISPLAYS

MSK–683 (CM)
MSK–966 (CM)
MSK–1123 (LM)
MSK–1137 (LM)

CSM GNC PRIMARY TAB



ASPO-2

MSK-683

GMTA	-	GREENWICH MEAN TIME (RECEIPT OF ANALOG DATA)	D H M S XX:XX:XX:XX
GETA	-	GROUND ELAPSED TIME (RECEIPT OF ANALOG DATA)	H M S XXXX:XX:XX
CTE	-	CENTRAL TIMING EQUIPMENT TIME	H M S XXXX:XX:XX
CMC	-	CM COMPUTER CLOCK	H M S XXXX:XX:XX
CMCB	-	CMC CLOCK MINUS ΔT UPDATED	H M S XXXX:XX:XX
GETC	-	GROUND ELAPSED TIME (RECEIPT OF COMPUTER WORDS)	
CMC ΔT	-	DIFFERENCE BETWEEN GETC AND CMC	S XXX.XXX
ISS	-	ISS MODE	OFF/TRN ON/CDU ZR/ CO ALN/FN ALN/ INTERTL/CAGE
OPT	-	OPTICS MODE	OFF/ZERO/CMC/MAN
CMC	-	RCS CONTROL MODE	AUTO/HOLD/FREE/SCS
ID	-	IDENTIFICATION OF DOWNLIST BEING TRANSMITTED	
*VERB	-	DSKY VERB DISPLAY	XX
*NOUN	-	DSKY NOUN DISPLAY	XX
*PRGM	-	DSKY PROGRAM NUMBER DISPLAY	XX
REG1, REG2, REG3	-	DSKY ROWS 1, 2, AND 3	±XXXXX
DAP	-	DIGITAL AUTOPILOT ACTIVE	SAT, RCS OR TVC
RATE	-	SELECTED MAXIMUM DAP RATE	X.X DEG/SEC
DB	-	SELECTED DAP DEADBAND	X.X DEG
VEH ACC	-	VEHICLE ACCELERATION	±XXX.X FPS^2
VG X, VG Y, VG Z	-	VELOCITY TO BE GAINED IN SM COORDINATES	±XXXX. FPS

*SEE CM SOFTWARE SECTION FOR FURTHER DEFINITION

PIPX, PIPY, PIPZ	-	X, Y, AND Z PIPA COUNTS	±XXXXX COUNTS
PIP T	-	PIPA TEMPERATURE	+XXX.X °F
TEV	-	TIME OF EVENT	H M S XXXX:XX:XX
TIG	-	TIME TO/FROM IGNITION	H M S XXXX:XX:XX
ISS ATT	-	ISS RESOLVER INDICATED ATTITUDE	+XXX.X DEG
ACDU	-	ACTUAL CDU ANGLES	+XXX.X DEG
FCDU	-	FINAL DESIRED CDU ANGLES	+XXX.X DEG
ERR CMC	-	COMPUTED ATTITUDE ERRORS TO FDAI	±XX.X DEG
ERR SCS	-	CREW SELECTED ERROR DISPLAY (CMC OR SCS GENERATED)	±XX.X DEG
RATE ENT	-	RATES COMPUTED IN ENTRY DAP	±XX.X DEG/SEC
RATE G/N	-	DAP COMPUTED BODY RATES	±X.XXX DEG/SEC
RATE SCS	-	SCS DETERMINED BODY RATES	±X.XXX DEG/SEC
GMB CMD	-	COMPUTER COMMANDED SPS ENGINE COMMANDS	±XX.XX DEG
OCDU DC	-	OCDU DAC OUTPUT FOR GMB CMD	±XX.XX DEG
SPS GMB	-	SPS GIMBAL POSITION OUTPUTS FOR GMB CMD	±XX.XX DEG
AT TVC	-	SCS AUTOMATIC CONTROL SPS GIMBAL COMMANDS	±X.XX DEG
MN TVC	-	SCS MANUAL CONTROL SPS GIMBAL COMMANDS	±X.XX DEG
SITE	-	SITE FROM WHICH DATA IS BEING RECEIVED	
DIF CUR	-	SPS GIMBAL MOTOR DIFFERENTIAL CLUTCH CURRENT	±XXX MA

ASPO-3

CMC MONITOR I H/S

0966

ID		GMTC		SITE		X/ROLL	Y/PITCH	Z/YAW	
		CTE				PIPA			
FGWD	0	GETA				DELV			
FGWD	1	GETC				VGIMU			
FGWD	2	CMCB							
FGWD	3	CMC				FCDU			
FGWD	4	TCMSV				DCDU			
FGWD	5	TLMSV				ACDU			
FGWD	6	TGO				ISS			
FGWD	7	TIG				ERROR			
FGWD	8	TEVNT				AK			
FGWD	9	PG	FL	WARN		ADOT			
FGWD	10	VB	NN	PRG		OMGAC			
FGWD	11			KK̄K		P ERR			
CHNL	11	R1		UPFST		I BIAS			
CHNL	12	R2		UPSW		P OCTL			
CHNL	13	R3		CMD		LM	ACTOFF		
CHNL	14					CSM	GMBCMD		
CHNL	30	REDO	DSTB11			HAPO	TCSI		
CHNL	31	FALRG	CHNL 77			HPER	TCDH		
CHNL	32	RSBBQ				LAT	TTPI		
CHNL	33	C31FW				LONG	TTPF		
						VMAGI	TMRK		
IMDE	30	HLDFG	INTEG TIME			VGTLI	TVHF		
IMDE	33					ΔT	VHFRNG NM		
OPTMDE		RCSFG	STARID1			CDH ΔH	ELEVN ANG		
DPDTR1			STARID2			VHF OPT	CNTRL ANG		
DPDTR2			CDU SHFT			ΔVLVX	Y	Z	
			CDU TRUN			ΔVR/PX	Y	Z	

ASPD-4

MSK-966

ID	-	IDENTIFICATION OF DOWNLIST BEING TRANSMITTED	
SITE	-	SITE FROM WHICH DATA IS BEING RECEIVED	
*FGWD 0 - FGWD 11	-	COMPUTER FLAGWORDS 0 THRU 11	$XXXXX_8$
*CHAN 11 - CHAN 14	-	COMPUTER OUTPUT CHANNELS	$XXXXX_8$
*CHAN 30 - CHAN 33	-	COMPUTER INPUT CHANNELS	$XXXXX_8$
*IMDE30, IMDE33	-	COMPUTER IMU STATUS REGISTERS	$XXXXX_8$
*OPTMDE	-	COMPUTER OPTICS STATUS REGISTER	$XXXXX_8$
*DPDTR1, DPDTR2	-	DATA FOR DAP SELECTION AND OPERATION	$XXXXX_8$
GMTC	-	GREENWICH MEAN TIME (RECEIPT OF CMC DATA)	D H M S XX:XX:XX:XX
CTE	-	CENTRAL TIMING EQUIPMENT TIME	H M S XXXX:XX:XX
GETA	-	GROUND ELAPSED TIME (RECEIPT OF ANALOG DATA)	H M S XXXX:XX:XX
GETC	-	GROUND ELAPSED TIME (RECEIPT OF COMPUTER WORDS)	H M S XXXX:XX:XX
CMCB	-	CMC CLOCK MINUS ΔT UPDATED	H M S XXXX:XX:XX
CMC	-	CM COMPUTER CLOCK	H M S XXX:XX:XX.XX
TCMSV	-	TIME OF CM STATE VECTOR	H M S XXX:XX:XX.XX
TLMSV	-	TIME OF LM STATE VECTOR	H M S XXX:XX:XX.XX
TGO	-	TIME TO CUTOFF	H M S XXX:XX:XX
TIG	-	TIME TO/FROM IGNITION	H M S XXX:XX:XX.XX
TEVNT	-	TIME OF EVENT	H M S XXX:XX:XX.XX
*PG	-	COMPUTER PROGRAM NUMBER	XX
FL	-	VERB/NOUN FLASHER STATUS	
WARN	-	CMC WARNING LAMP STATUS	
PRG	-	PROGRAM ALARM LAMP STATUS	
KK̄K	-	UPLINK DATA STATUS	
UPFST	-	BLOCK INLINK DISCRETE STATUS	
UPSW	-	UPLINK ACCEPT/BLOCK SWITCH STATUS	
CMD	-	UPLINK TOO FAST STATUS	
*VB	-	DSKY VERB DISPLAY	XX
*NN	-	DSKY NOUN DISPLAY	XX
R1, R2, & R3	-	DSKY ROW 1, ROW 2, AND ROW 3 DISPLAYS	±XXXXX
REDO	-	NUMBER OF RESTARTS	$XXXXX_8$
RSBBQ	-	VALUE OF BBANK AND Q REGISTERS AT THE TIME OF A RESTART	$XXXXX_8$
DSTB11	-	DISPLAY TABLE OF DSKY STATUS LIGHTS $X0400_8$ = PROGRAM CAUTION, $X0200_8$ = TRACKER WARNING, $X0020_8$ = NO ATTITUDE, $X0040_8$ = GIMBAL LOCK	$XXXXX_8$
*FALRG	-	1ST, 2ND AND MOST RECENT ALARM CODES	$XXXXX_8$
CHNL 77	-	CHANNEL 77 - RESTART MONITOR	$XXXXX_8$
C31FW	-	SWITCH OVERRIDE BUFFER FOR SC CONTROL, CMC MODE AND OPTICS MODE	$XXXXX_8$
*HLDFLG	-	DELAY TIME FOR CDU TRANSIENT CHECK AFTER MARK (CDUCKWD)	$XXXXX_8$
INTEG TIME	-	TIME TO WHICH STATE VECTOR IS PRESENTLY INTEGRATED	H M S XXX:XX:XX.XX
*RCSFG	-	DATA FOR RCS DAP	$XXXXX_8$
STARID1	-	IDENTIFICATION NUMBER OF STAR 1	XXX_8
STARID2	-	IDENTIFICATION NUMBER OF STAR 2	XXX_8
CDU SHAFT	-	OPTICS SHAFT ANGLE	±XXX.XX DEG
CDU TRUN	-	OPTICS TRUNNION ANGLE	±XX.XXX DEG

*SEE CM SOFTWARE SECTION FOR FURTHER DEFINITION

ASPD-5

PIPA	-	PIPA COUNTS	±XXXXX COUNTS
DELV	-	VALUES OF PIPA'S AT LAST READING, CORRECTED FOR SCALE FACTOR ERROR AND BIAS	±XXXX.X FPS
VGIMU	-	VELOCITY TO BE GAINED IN SM COORDINATES	±XXXX.X FPS
FCDU	-	FINAL DESIRED CDU ANGLES	+XXX.XX DEG
DCDU	-	DESIRED CDU ANGLES	+XXX.XX DEG
ACDU	-	ACTUAL CDU ANGLES	+XXX.XX DEG
ISS	-	LX RSVR ANGLES	±XXX.XX DEG
ERROR	-	RCS DAP FOLLOWING ERRORS	±X.XXX DEG
AK	-	RCS DAP ATTITUDE ERRORS OR TVC DAP ATTITUDE ERRORS	±X.XXX DEG
ADOT	-	RCS DAP COMPUTED CONTROL AXIS RATES OR TVC DAP COMPUTED BODY RATES (OMEGAB)	±X.XXX DEG/SEC
OMGAC	-	RCS DAP CONTROL AXIS RATE COMMANDS (WBODY) OR TVC DAP BODY RATE COMMANDS FROM CROSS PRODUCT STEERING (OMEGAC)	±X.XXX DEG/SEC
ERR	-	MEASURED BIAS MINUS LOADED COMPENSATION	±X.XXXX FT/SEC
BIAS	-	MEASURED BIAS (10 SECOND INTERVALS)	±X.XXXX FT/SEC
OCTL	-	OCTAL VALUE OF LOADED BIAS COMPENSATION	$XXXXX_8$
LM	-	PRESENT MASS OF THE LM	XXXXX LBS
CSM	-	PRESENT MASS OF THE CSM	XXXXX LBS
ACTOFF	-	SPS GIMBAL TRIMS	±XX.XXX DEG
GMBCMD	-	COMPUTER COMMANDED SPS ENGINE COMMANDS	±XX.XXX DEG
HAPO	-	ALTITUDE AT APOGEE	+XXXX.X NM
HPER	-	ALTITUDE AT PERIGEE	+XXXX.X NM
LAT	-	LATITUDE OF LANDMARK	±XX.XXX DEG
LONG	-	LONGITUDE OF LANDMARK	±XXX.XX DEG
VMAGI	-	PRESENT INERTIAL VELOCITY (TLI)	XXXXX FT/SEC
VGTLI	-	VELOCITY TO BE GAINED (TLI)	XXXXX FT/SEC

ΔT	-	DIFFERENCE BETWEEN GETC AND CMC	M S XXX:XX.XXX
CDH ΔH	-	DIFFERENCE IN ALTITUDE BETWEEN VEHICLES AT CDH	±XX.XX NM
VHF	-	VHF MARKS INCORPORATED IN STATE	XX
OPT	-	OPTICS MARKS INCORPORATED IN STATE	XX
Δ VLV	-	X, Y, AND Z COMPONENTS OF DELTAV IN LOCAL VERTICAL COORDINATES	±XXXX.X FT/SEC
ΔVR/P	-	X, Y, AND Z COMPONENTS OF DELTAV FROM LAMBERT SOLUTION IN SM COORDINATES	±XXXX.X FT/SEC
TCSI	-	TIME OF INITIATION OF CSI	H M S XXX:XX:XX.XX
TCDH	-	TIME OF INITIATION OF CDH	H M S XXX:XX:XX.XX
TTPI	-	TIME OF INITIATION OF TPI	H M S XXX:XX:XX.XX
TTPF	-	TIME OF INITIATION OF TPF	H M S XXX:XX:XX.XX
TMRK	-	TIME OF LAST OPTICS MARK	H M S XXX:XX:XX.XX
TVHF	-	TIME OF LAST VHF MARK	H M S XXX:XX:XX.XX
VHFRNG	-	RAW VHF RANGE TO LM	±XXX.XX NM
ELEVN ANG	-	DESIRED LOS ANGLE AT TPI	±XXX.XX DEG
CNTRL ANG	-	ORBITAL CENTRAL ANGLE OF THE PASSIVE VEHICLE DURING TRANSFER FROM TPI TO INTERCEPT	±XXX.XX DEG

*SEE CM SOFTWARE SECTION FOR FURTHER DEFINITION

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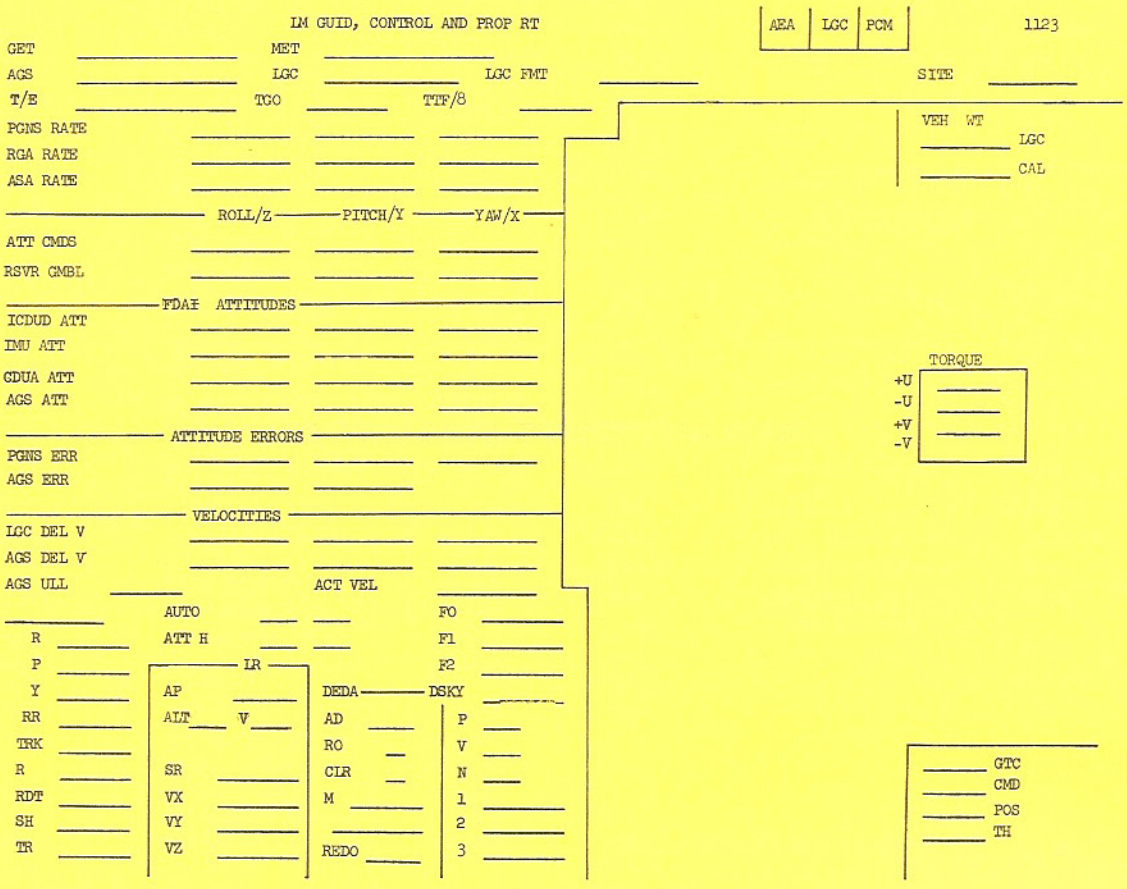


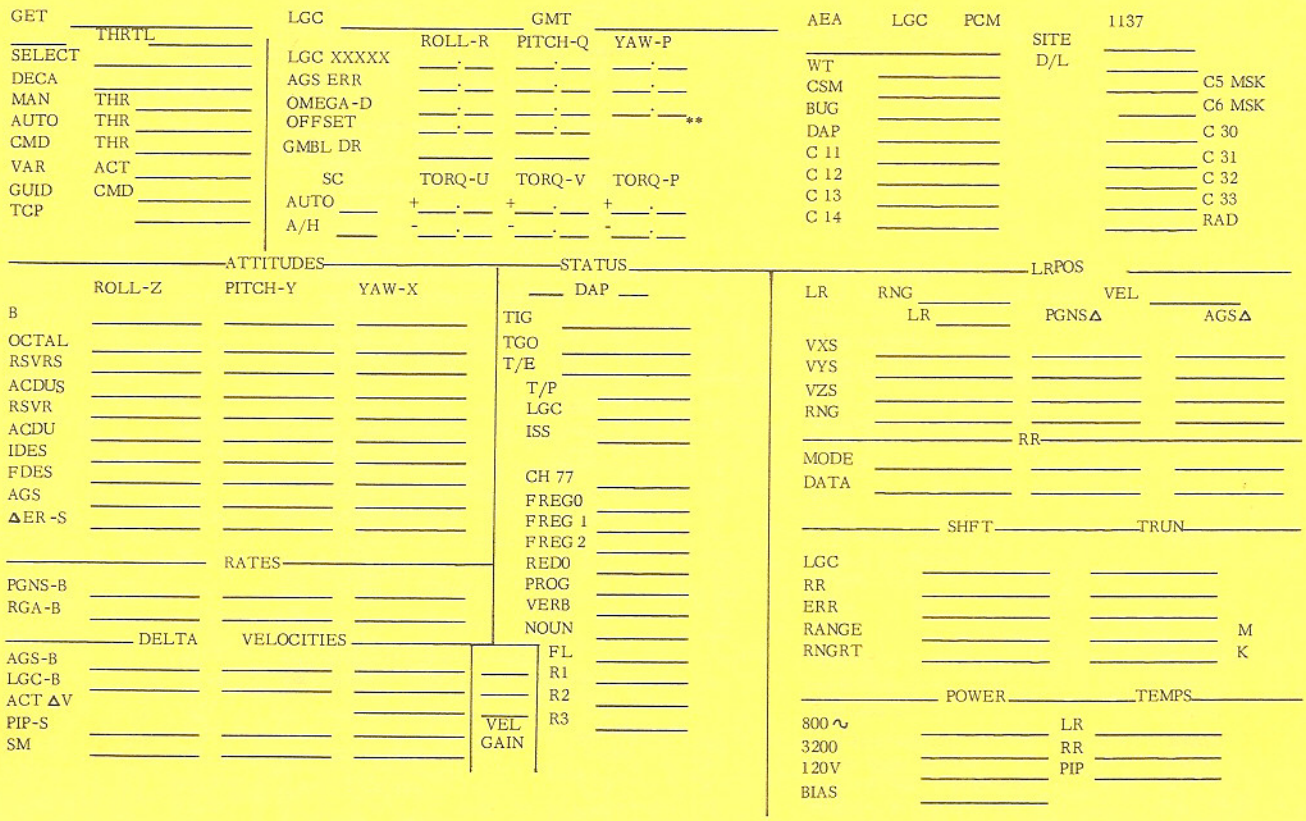
ASPO-8

MSK-1123

GET	-	GROUND ELAPSED TIME	H M S XXX:XX:XX
MET	-	MISSION ELAPSED TIME	H M S XXX:XX:XX
AGS	-	ABORT GUIDANCE SYSTEM TIME	H M S XXX:XX:XX
LGC	-	LM GUIDANCE COMPUTER TIME	H M S XXX:XX:XX
LGC FMT	-	IDENTIFICATION OF DOWNLIST BEING TRANSMITTED	
SITE	-	IDENTIFICATION OF SITE FROM WHICH DATA IS BEING RECEIVED	
TGO	-	TIME TO GO UNTIL ENGINE CUTOFF	M S XX:XX
TTF/8	-	TIME TO GO UNTIL END OF PHASE (DESCENT PROGRAMS)	M S XX:XX
T/E	-	TIME OF EVENT	H M S XXX:XX:XX
PGNS RATE	-	ROLL, PITCH, YAW DAP RATES	XX.X DEG/SEC
RGA	-	AGS BODY MOUNTED RATE GYRO (OUTPUT)	XX.X DEG/SEC
ASA	-	AGS ABORT SENSING ASSEMBLY (BODY RATES)	XX.X DEG/SEC
ATT CMDS	-	LGC ATTITUDE COMMANDS	XX.X DEG
RSVR GMBL	-	1X RESOLVER GIMBAL ANGLES	XXX.X DEG
ICDUD ATT	-	DESIRED CDU ANGLES TO THE DAP	XXX.X DEG
CDUA ATT	-	ACTUAL CDU ANGLES	XXX.X DEG
IMU ATT	-	1X RESOLVER GIMBAL ANGLES	XXX.X DEG
AGS ATT	-	ABORT GUIDANCE SYSTEM BODY ANGLES	XXX.X DEG
PGNS ERR	-	CDU-DAC OUTPUT	XX.X DEG
AGS ERR	-	ABORT GUIDANCE SYSTEM ATTITUDE ERRORS	XXX.X DEG
LGC DEL V	-	PIPA OUTPUT FOR A 2 SECOND INTERVAL	XX.X FT/SEC
AGS DEL V	-	ABORT GUIDANCE SYSTEM MEASURED VELOCITY	XX.X FT/SEC
AGS ULL	-	ABORT GUIDANCE ULLAGE MEASUREMENT	XX.XX FT/SEC
ACT VEL	-	ACCUMULATED VELOCITY ALONG THRUST	XX.X FT/SEC
AUTO	-	AUTO STABILIZATION MODE STATUS	XX/BLANK
R, P, Y	-	ROLL, PITCH AND YAW ACHIEVED FROM PULSES, DIRECT OR AUTO (NORM)	±XXX.X DEG
ATT H	-	ATTITUDE HOLD MODE STATUS	XX/BLANK
*F0	-	FIRST	
*F1	-	SECOND	
*F2	-	MOST RECENT	
*RR	-	RADAR MODE FLAGWORD (RADMODES)	$XXXXX_8$
TRK	-	RADAR TRACK ENABLE	CH 12 B 14
RDT	-	RENDEZVOUS RADAR RANGE RATE	XXXX FT/SEC
R	-	RENDEZVOUS RADAR RANGE	XXX.XX NM
SH	-	RENDEZVOUS RADAR SHAFT ANGLE	±XXX DEG
TR	-	RENDEZVOUS RADAR TRUNNION ANGLE	±XXX DEG
AP	-	LANDING ANTENNA POSITION	1 OR 2
ALT	-	LR ALTITUDE DATA GOOD	BLANK/XX
V	-	LR VELOCITY DATA GOOD	BLANK/XX
SR	-	LANDING RADAR RANGE	XXXXX FT
V_X, V_Y, V_Z	-	LANDING RADAR VELOCITIES	±XXXXX FT/SEC
DEDA	-	AGS DSKY	
AD	-	ADDRESS	
RO	-	READOUT	
CLR	-	CLEAR	
M	-	REGISTER 5 DIGIT CONTENTS	
REDO	-	NUMBER OF LGC RESTARTS	
DSKY	-	STATUS OF DSKY DISPLAYS	BLANK/FLSH
*P	-	PROGRAM	
*V	-	VERB	
*N	-	NOUN	
1 2 3	-	ROW 1, 2, AND 3	
LGC	-	LGC CALCULATED LM WEIGHT	XXXXX LBS
CAL	-	GROUND CALCULATED LM WEIGHT	XXXXX LBS
TORQUE +U, -U, +V, -V	-	ACCUMULATED SUM OF + AND - COMMANDED TORQUE TIME ABOUT CONTROL AXES	XX.X SEC
TH	-	GROUND CALCULATED THRUST	XXXXX LBS
GTC	-	GUIDANCE THRUST COMMAND	XXX %
CMD	-	SUM OF MANUAL AND AUTO THROTTLE COMMAND	XXX %
POS	-	THROTTLE POSITION	XXX %

*SEE LM SOFTWARE SECTION FOR FURTHER DEFINITION

ASPO-9



ASPO-10

MSK-1137

GET	-	GROUND ELAPSED TIME	H M S XXX:XX:XX
LGC	-	LM COMPUTER CLOCK	H M S XXX:XX:XX
GMT	-	GREENWICH MEAN TIME	H M S XXX:XX:XX
SITE	-	SITE FROM WHICH DATA IS BEING RECEIVED	
D/L	-	DOWNLIST IDENTIFICATION	
SELECT	-	THROTTLE SELECT SWITCH STATUS	AUTO/BLANK
DECA	-	DESCENT THROTTLE COMMAND	±XXX.XX
MAN THR	-	MANUAL THROTTLE COMMAND	XXX%
AUTO THR	-	AUTO THROTTLE COMMAND	XXX%
CMD THR	-	TOTAL THROTTLE COMMAND (MAN THR + AUTO THR)	XXX%
VAR ACT	-	VARIABLE ACTUATOR POSITION	XXX%
GUID CMD	-	LGC COMMANDED THRUST	XXX%
TCP	-	THRUST CHAMBER PRESSURE	XXX%
LGC XXXXX - ERR	=	TOTAL OR DAP FOLLOWING ATTITUDE ERRORS	±XX.X DEG
- RATES	=	LGC COMPUTED BODY RATES	±XX.X DEG/SEC
AGS ERR	-	AGS POSITIONAL ERROR	±XXX.X DEG
OMEGA-D	-	DESIRED BODY RATES FOR AUTOMATIC MANEUVER	±X.XX DEG/SEC
OFFSET	-	COMPUTED ANGULAR ACCELERATION ABOUT Y AND Z BODY AXES DUE TO THE ENGINE	±XX.X DEG/SEC^2
GMBL DR	-	DIRECTION OF ENGINE BELL MOTION	±R & ±P
A/H	-	ATTITUDE HOLD MODE STATUS	XX/BLANK
AUTO	-	AUTO STABILIZATION MODE STATUS	XX/BLANK
+ TORQ-U, TORQ-V, TORQ-P	-	CUMMULATIVE SUM OF POSITIVE COMMANDED TORQUE ABOUT CONTROL AXES U, V, AND P RESPECTIVELY	XX.XX SECS
- TORQ-U, TORQ-V, TORQ-P	-	CUMMULATIVE SUM OF NEGATIVE COMMANDED TORQUE ABOUT CONTROL AXES U, V, AND P RESPECTIVELY	XX.XX SECS
**	-	DAP DATA LOAD	

WT	-	MASS OF THE LM	XXXXX LBS
CSM	-	MASS OF THE CSM	XXXXX LBS
BUG	-	FLAGWORD FOR ENABLING ABORT SWITCHES MONITOR & AUTO THROTTLE MONITOR	$000XX_8$
*DAP	-	DAP FLAGWORD (DAPBOOLS)	$XXXXX_8$
		LM COMPUTER OUTPUT CHANNELS	$XXXXX_8$
*C11 - C14	-	LM COMPUTER OUTPUT CHANNELS	$XXXXX_8$
*C5MSK - C6MSK	-	FLAGWORDS FOR INHIBITING DAP FIRING OF JETS	XXX_8
*C30 - C33	-	LM COMPUTER INPUT CHANNELS	$XXXXX_8$
*RAD	-	RADAR FLAGWORD(RADMODES)	$XXXXX_8$
B	-	ΔPIPA COUNTS/Δ TIME. PIPA FREE FALL BIAS (GROUND COMPUTED)	±XXX.XXX CM/SEC^2
OCTAL	-	COMPUTED OCTAL LOADS FOR LGC PIPA BIAS REGISTERS	$XXXXX_8$
RSVRS	-	GIMBAL RESOLVER INDICATED ANGLES	+XXX.XX DEG
ACDUS	-	ACTUAL CDU ANGLES	+XXX.XX DEG
RSVR	-	GIMBAL RESOLVER INDICATED ANGLES IN FDAI COORDINATES	+XXX.XX DEG
ACDU	-	GIMBAL ANGLES TRANSFORMED TO FDAI COORDINATES	+XXX.XX DEG
IDES	-	INTERMEDIATE DESIRED CDU ANGLES TRANSFORMED TO FDAI COORDINATES	+XXX.XX DEG
FDES	-	FINAL DESIRED CDU ANGLES TRANSFORMED TO FDAI COORDINATES	+XXX.XX DEG
AGS	-	AGS EULER ANGLES TRANSFORMED TO FDAI COORDINATES	+XXX.XX DEG
ΔER-S	-	DIFFERENCE BETWEEN PGNS EULER ANGLES AND AGS EULER ANGLES	±XX.XX DEG

*SEE LM SOFTWARE SECTION FOR FURTHER DEFINITION

ASPO-11

PGNS-B	-	DAP COMPUTED BODY RATES	±XX.XX DEG/SEC	LRPOS	-	LANDING RADAR ANT POSITION	ONE/TWO
RGA-B	-	AGS RATE GYRO OUTPUTS IN BODY COORDINATES	±XX.X DEG/SEC	LR RNG	-	STATUS OF LANDING RADAR RANGE DATA	GOOD/BAD
AGS-B	-	AGS INDICATED LINEAR VELOCITY IN BODY COORDINATES	±XX.X FT/SEC	VEL	-	STATUS OF LANDING RADAR VELOCITY DATA	GOOD/BAD
LGC-B	-	ACCUMULATED PIPA COUNTS WHILE SERVICER IS RUNNING IN BODY AXIS COORDINATES	±XX.X FT/SEC	VXS, VYS, VZS	-	LR VELOCITY DATA CONVERTED TO STABLE MEMBER COORDINATES	±XXXX FT/SEC
ACT ΔV	-	ACTUAL DELTA V GAINED (GROUND COMPUTED)	XX.X FT/SEC	RNG	-	LANDING RADAR SLANT RANGE	XXXXX FT
PIP-S	-	PIPA COUNTS	$XXXX_{10}$	PGNSΔ	-	LR MINUS PGNS VELOCITIES CORRECTED FOR LUNAR GRAVITY IN STABLE MEMBER COORDINATES	±XXXX FT/SEC
SM	-	ACCUMULATED PIPA COUNTS OVER 2 SECONDS IN STABLE MEMBER COORDINATE	±XX.X FT/SEC	AGSΔ	-	LR MINUS AGS VELOCITIES CORRECTED FOR LUNAR GRAVITY IN STABLE MEMBER COORDINATES	±XXXX FT/SEC
DAP	-	LEFT - POSITION OF GUIDANCE AND CONTROL SWITCH	AGS/PGNS				
		RIGHT - STATUS OF THE DAP	ON/OFF	MODE	-	STATUS OF RENDEZVOUS RADAR	LGC/AUTO/MAN/SLEW EN/NO EN ONE/TWO
TIG	-	TIME TO IGNITION	H M S XXX:XX:XX	DATA	-	STATUS OF RENDEZVOUS RADAR DATA	GOOD/BAD TRK/NO TRK LO/HIGH
TGO	-	TIME TO ENGINE CUTOFF	S XXXXX.	_____/CDUF	-	STATUS OF RR CDU'S	BLANK/CDUF
T/E	-	TIME OF LAST/NEXT SIGNIFICANT EVENT	H M S XXX:XX:XX	LGC	-	RENDEZVOUS RADAR ANTENNA POSITION (CDU)	±XXX.X DEG
T/P	-	TIME TO END OF PHASE (DESCENT ONLY)	S XXXXX.	RR	-	RENDEZVOUS RADAR ANTENNA POSITION IN FDAI COORDINATES	±XXX.X DEG
LGC	-	LGC WARNING LAMP STATUS		ERR	-	COMPUTER COMMANDED RENDEZVOUS RADAR ANTENNA RATE	±XX.XX DEG/SEC
ISS	-	ISS WARNING LAMP STATUS					
				RANGE	-	RENDEZVOUS RADAR RANGE	XXX.XX NMI
*CH77	-	DEFINITION FOR CAUSE OF LGC WARNING	$XXXXX_8$	RNGRT	-	RENDEZVOUS RADAR RANGE RATE	±XXXX FT/SEC
*FREG0, FREG1, FREG2	-	1ST, 2ND, AND MOST RECENT ALARM CODE	$XXXXX_8$	800 ∿	-	800 ∿ VOLTAGE	XX.X VOLTS
*REDO	-	NUMBER OF RESTARTS	$XXXX_8$	3200	-	3200 ∿ VOLTAGE	XX.X VOLTS
*PROG	-	COMPUTER PROGRAM NUMBER	XX	120V	-	120 VDC PIPA SUPPLY VOLTAGE	XXX VOLTS
*VERB	-	DSKY VERB DISPLAY	XX	BIAS	-	TM BIAS VOLTAGE	X.XX VOLTS
*NOUN	-	DSKY NOUN DISPLAY	XX	LR	-	LANDING RADAR ANTENNA TEMPERATURE	±XXX.X °F
FL	-	INDICATES WHETHER OR NOT VERB/NOUN FLASHER IS ON	FLSH/BLANK	RR	-	RENDEZVOUS RADAR ANTENNA TEMPERATURE	±XXX.X °F
*R1, R2, R3	-	DSKY ROW 1, ROW 2, AND ROW 3 DISPLAYS	±XXXXX	PIP	-	PIPA TEMPERATURE	+XXX.X °F

*SEE LM SOFTWARE SECTION FOR FURTHER DEFINITION.